

An introduction to particle simulation of rare events

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Outline

- 1 Introduction, motivations
- 2 The heuristic of particle methods
- 3 Particle Feynman-Kac models
- 4 Stochastic models and methods
- 5 Some convergence results
- 6 Some references

1 Introduction, motivations

- Some rare event problems
- Stochastic models
- Importance sampling techniques

2 The heuristic of particle methods

3 Particle Feynman-Kac models

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Rare event analysis

- **Stochastic process $X \oplus$ Rare event A :**

$$\text{Proba}(X \in A) \quad \& \quad \text{Law}((X_0, \dots, X_t) \mid X \in A)$$

▷ **engineering/physics/biology/economics/finance :**

- *Finance* : ruin/default probabilities, financial crashes, eco. crisis,...
- *engineering* : networks overload, breakdowns, engines failures,...
- *Physics* : climate models, directed polymer conformations, particle in absorbing medium, ground states of Schroedinger models.
- *Statistics* : tail probabilities, extreme random values.
- *Combinatorics* : Complex enumeration problems.

- **Process strategies \in Rare event \Rightarrow Control and prediction.**

$$X_t = F_t(X_{t-1}, W_t) \rightarrow \text{Law}((W_0, \dots, W_t) \mid X \in A)$$

Only 2 Ingredients

- 1 Physical/biological/financial process : queuing network, portfolio, volatility process, stock market evolutions, interacting/exchange economic models ...
- 1 Potential function (energy type, indicator, restrictions): critical level crossing, penalties functions, constraints subsets, performance levels, long range dependence...

Objectives

- Estimation of the probability of the rare event.
- Computing the full distributions of the path of the process evolving in the critical regime \rightsquigarrow prediction \oplus control.

Twisted Monte Carlo methods

$$\mathbb{P}(X \in A) = 10^{-10} \rightsquigarrow \text{Find } \mathbb{Q} \text{ s.t. } \mathbb{Q}(A) \simeq 1$$

Elementary Monte Carlo estimate X^i iid \mathbb{Q}

$$\mathbb{P}(A) := \int \frac{d\mathbb{P}}{d\mathbb{Q}}(x) 1_A(x) \mathbb{Q}(dx) \simeq \mathbb{P}^N(A) := \frac{1}{N} \sum_{1 \leq i \leq N} \frac{d\mathbb{P}}{d\mathbb{Q}}(X^i) 1_A(X^i)$$

$$\text{Variance} \simeq \int \frac{d\mathbb{P}}{d\mathbb{Q}}(x) 1_A(x) \mathbb{P}(dx) \quad (\text{ex. cross-entropy : } \mathbb{Q} \in \{\mathbb{Q}_a, a \in \mathcal{A}\})$$

Drawbacks

- Huge variance if \mathbb{Q} badly chosen \rightsquigarrow optimal choice $\mathbb{Q}(dx) \propto 1_A(x)\mathbb{P}(dx)$.
- Need to twist the original reference process X .
- Stochastic evolution $X = (X_0, \dots, X_n)$

$$\frac{d\mathbb{P}_n}{d\mathbb{Q}_n}(X) := \prod_{k=0}^n \frac{p_k(X_k | X_{k-1})}{q_k(X_k | X_{k-1})} \quad \text{degenerate product martingale w.r.t. } n$$

Summary

1 Introduction, motivations

2 The heuristic of particle methods

- Flow of optimal twisted measures
- 5 Examples of flow of target measures
- 3 types of occupation measures
- Some equivalent stochastic algorithms

3 Particle Feynman-Kac models

4 Stochastic models and methods

5 Some convergence results

6 Some references

Flow of measure with increasing sampling complexity

- Rare event = cascade/series of intermediate less-rare events
(\uparrow energy levels, physical gateways, index level crossings).
- Conditional probability flow = flow of optimal twisted measures
 $n \rightarrow \eta_n = \text{Law}(\text{process} \mid \text{series of } n \text{ intermediate events})$
- Rare event probabilities= Normalizing constants.

Particle methods

(Sampling a genealogical type default tree model \oplus % success or default)

- Explorations/Local search propositions of the solution space.
- Branching-Selection individuals $\in \uparrow$ critical regimes.

5 Examples of flow of target measures

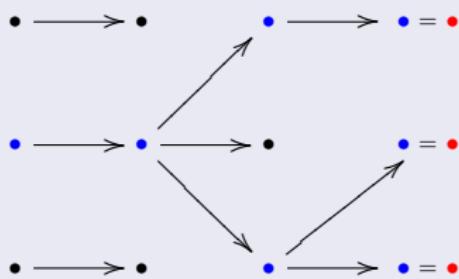
- ① $\eta_n = \text{Law}((X_0, \dots, X_n) \mid \forall 0 \leq p \leq n \quad X_p \in A_p)$
- ② $\eta_n(dx) \propto e^{-\beta_n V(x)} \lambda(dx)$ with $\beta_n \uparrow$
- ③ $\eta_n(dx) \propto 1_{A_n}(x) \lambda(dx)$ with $A_n \downarrow$
- ④ $\eta_n = \text{Law}_\pi^K((X_0, \dots, X_n) \mid X_n = x_n).$
- ⑤ $\eta_n = \text{Law}(X \text{ hits } B_n \mid X \text{ hits } B_n \text{ before } A)$

5 particle heuristics :

- ① M_n -local moves \oplus individual selections $\in A_n$ i.e. $\sim G_n = 1_{A_n}$
- ② MCMC local moves $\eta_n = \eta_n M_n \oplus$ individual selections $\propto G_n = e^{-(\beta_{n+1} - \beta_n)V}$
- ③ MCMC local moves $\eta_n = \eta_n M_n \oplus$ individual selections $\propto G_n = 1_{A_{n+1}}$
- ④ M -local moves \oplus Selection $G(x_1, x_2) = \frac{\pi(dx_2)K(x_2, dx_1)}{\pi(dx_1)M(x_1, dx_2)}$
- ⑤ M_n -local moves \oplus Selection-branching on upper/lower levels B_n .

Interaction/branch. process \hookrightarrow 3 types of occupation measures

($N = 3$)



- Current population $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{\xi_n^i} \leftarrow i\text{-th individual at time } n$
- Genealogical tree model $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i)} \leftarrow i\text{-th ancestral line}$
- Complete genealogical tree model $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_0^i, \xi_1^i, \dots, \xi_n^i)}$
- \oplus Empirical mean potentials [success % ($G_n = 1_A$)] $\hookrightarrow \frac{1}{N} \sum_{i=1}^N G_n(\xi_n^i)$

Equivalent Stochastic Algorithms :

- Genetic and evolutionary type algorithms.
- Spatial branching models, subset splitting techniques.
- Sequential Monte Carlo methods, population Monte Carlo models.
- Diffusion Monte Carlo (DMC), Quantum Monte Carlo (QMC), ...
- Some botanical names $\sim \neq$ application domain areas :
bootstrapping, selection, pruning-enrichment, reconfiguration, cloning, go with the winner, spawning, condensation, grouping, rejuvenations, harmony searches, biomimetics, splitting, ...

\Updownarrow

1950 \leq [(Meta)Heuristics] \leq 1996 \leq Feynman-Kac mean field particle model

Summary

- 1 Introduction, motivations
- 2 The heuristic of particle methods
- 3 Particle Feynman-Kac models
 - Some notation
 - Asymptotic Analysis
 - Some workout examples
 - Sensitivity analysis
- 4 Stochastic models and methods
- 5 Some convergence results
- 6 Some references

Notation

E measurable state space, $\mathcal{P}(E)$ proba. on E , $\mathcal{B}(E)$ bounded meas. functions

- $(\mu, f) \in \mathcal{P}(E) \times \mathcal{B}(E) \quad \longrightarrow \quad \mu(f) = \int \mu(dx) f(x)$
- $M(x, dy)$ **integral operator over E**

$$M(f)(x) = \int M(x, dy)f(y)$$

$$[\mu M](dy) = \int \mu(dx)M(x, dy) \quad (\implies [\mu M](f) = \mu[M(f)])$$

- **Bayes-Boltzmann-Gibbs transformation :** $G : E \rightarrow [0, \infty[$ with $\mu(G) > 0$

$$\Psi_G(\mu)(dx) = \frac{1}{\mu(G)} G(x) \mu(dx)$$

E finite \iff Matrix notations $\mu = [\mu(1), \dots, \mu(d)]$ and $f = [f(1), \dots, f(d)]'$

Infinite Population $N \uparrow \infty$ " = " Feynman-Kac measures $\simeq (G_n, M_n)$

- Current population:

$$\eta_n^N(f) := \frac{1}{N} \sum_{i=1}^N f(\xi_n^i) \xrightarrow{N \uparrow \infty} \eta_n(f) := \frac{\gamma_n(f)}{\gamma_n(1)}$$

with [Potential functions G_n] & [X_n Markov chain \sim transitions M_n]

$$\gamma_n(f) := \mathbb{E} \left(f_n(X_n) \prod_{0 \leq p < n} G_p(X_p) \right)$$

- Genealogical tree occupation measures:

$$\frac{1}{N} \sum_{i=1}^N \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i)} \xrightarrow{N \uparrow \infty} d\mathbb{Q}_n := \frac{1}{\mathcal{Z}_n} \left\{ \prod_{0 \leq p < n} G_p(X_p) \right\} d\mathbb{P}_n$$

- Normalizing constants: $\prod_{0 \leq p < n} \eta_p^N(G_p) \xrightarrow{N \uparrow \infty} \mathcal{Z}_n = \gamma_n(1)$

Feynman-Kac models \supset ALL of the above heuristics

Example : $G_n = 1_{A_n}$ and X_n Markov chain

- Normalizing constants:

$$\gamma_n(1) = \mathbb{P}(n\text{-th rare event}) = \mathbb{P}(X_p \in A_p, 0 \leq p < n)$$

- n -th time marginals:

$$\eta_n = \text{Law}(X_n \mid n\text{-th rare event}) = \text{Law}(X_n \mid X_p \in A_p, 0 \leq p < n)$$

- Path space measures:

$$\mathbb{Q}_n = \text{Law}((X_p)_{0 \leq p \leq n} \mid n\text{-th rare event}) = \text{Law}((X_p)_{0 \leq p \leq n} \mid X_p \in A_p, p < n)$$

- Note : Including the n -th rare event level set

\rightsquigarrow Updated measures $\widehat{\gamma}_n, \widehat{\eta}_n, \widehat{\mathbb{Q}}_n$ with $\prod_{0 \leq p \leq n}$

Another "detailed" static example

Restriction of measures : $A_n \downarrow$ (Ex.: $A_n = [a_n, \infty[\rightsquigarrow$ tails probab.)

$$\eta_n(dx) = \frac{1}{Z_n} 1_{A_n}(x) \lambda(dx)$$

Feynman-Kac representation :

$$\eta_n(f) := \frac{\gamma_n(f)}{\gamma_n(1)} \quad \text{with} \quad \gamma_n(f) := \mathbb{E} \left(f_n(X_n) \prod_{0 \leq p < n} 1_{A_{p+1}}(X_p) \right)$$

and

$$\mathbb{P}(X_n \in dx_n \mid X_{n-1} = x_{n-1}) = M_n(x_{n-1}, dx_n) \quad \text{with} \quad \eta_n = \eta_n M_n$$

Note :

$$\begin{aligned} Z_n &= \lambda(A_n) \\ &= \underbrace{\frac{\lambda(1_{A_n} 1_{A_{n-1}})}{\lambda(1_{A_{n-1}})}}_{\eta_{n-1}(1_{A_n})} \times Z_{n-1} \stackrel{(A_0=E)}{=} \prod_{0 \leq p < n} \eta_p(1_{A_{p+1}}) \end{aligned}$$

Sensitivity analysis

$$\theta \mapsto M_n(x_{n-1}, dx_n) = p_n^\theta(x_{n-1}, x_n) \lambda_n^X(dx_n) \quad \text{and} \quad G_n(x) = G_n^\theta(x)$$

↓

Parametric Feynman-Kac models : $(G_n, \mathbb{Q}_n, \gamma_n, \eta_n, \dots) \rightsquigarrow (G_n^\theta, \mathbb{Q}_n^\theta, \gamma_n^\theta, \eta_n^\theta, \dots)$

$$\frac{\partial}{\partial \theta} \log \widehat{\gamma}_n^\theta(1) = \widehat{\mathbb{Q}}_n^\theta(F_n^\theta) \quad \text{and} \quad \frac{\partial}{\partial \theta} \widehat{\mathbb{Q}}_n^\theta(\varphi_n) = \widehat{\mathbb{Q}}_n^\theta \left(F_n^\theta [\varphi_n - \widehat{\mathbb{Q}}_n^\theta(\varphi_n)] \right)$$

with the additive functional

$$F_n^\theta(x_0, \dots, x_n) := \sum_{0 \leq k \leq n} f_k^\theta(x_{k-1}, x_k)$$

$$f_k^\theta(x_{k-1}, x_p) := \frac{\partial \log G_p^\theta(x_k)}{\partial \theta} + \frac{\partial \log p_k^\theta(x_{k-1}, x_k)}{\partial \theta}$$

- Path space models $\mathbb{P}_n := \text{Law}(X_0, \dots, X_n)$

$$d\mathbb{Q}_n := \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} G_p(X_p) \right\} d\mathbb{P}_n$$

- Hyp. : $M_n(x_{n-1}, dx_n) = H_n(x_{n-1}, x_n) \lambda_n(dx_n)$

$$\Rightarrow \mathbb{Q}_n(d(x_0, \dots, x_n)) = \eta_n(dx_n) M_{n, \eta_{n-1}}(x_n, dx_{n-1}) \dots M_{1, \eta_0}(x_1, dx_0)$$

with the backward transitions :

$$M_{p+1, \eta}(x, dx') \propto G_p(x') H_{p+1}(x', x) \eta(dx')$$

- Particle estimates** \sim Ancestral tree or the complete genealogical tree :

$$\mathbb{Q}_n^N(d(x_0, \dots, x_n)) = \eta_n^N(dx_n) M_{n, \eta_{n-1}^N}(x_n, dx_{n-1}) \dots M_{1, \eta_0^N}(x_1, dx_0)$$

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 - McKean distribution models
 - Mean field particle interpretations
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Flows of Feynman-Kac measures

- A two step correction prediction model

$$\eta_n \xrightarrow{\text{Updating-correction}} \widehat{\eta}_n = \Psi_{G_n}(\eta_n) \xrightarrow{\text{Prediction/Markov transport}} \eta_{n+1} = \widehat{\eta}_n M_{n+1}$$

- Selection nonlinear transport formulae

$$\Psi_{G_n}(\eta_n) = \eta_n S_{n,\eta_n}$$

with, for **any** $\epsilon_n = \epsilon_n(\eta_n) \in [0, 1]$ s.t. $\epsilon_n G_n \leq 1$

$$S_{n,\eta_n}(x, \cdot) := \epsilon_n G_n(x) \delta_x + (1 - \epsilon_n G_n(x)) \Psi_{G_n}(\eta_n)$$



$$\eta_{n+1} = \eta_n (S_{n,\eta_n} M_{n+1}) := \eta_n K_{n+1,\eta_n}$$

Nonlinear Markov chains $\eta_n = \text{Law}(\overline{X}_n)$ =Perfect sampling algorithm

- Nonlinear transport formulae :

$$\eta_{n+1} = \eta_n K_{n+1, \eta_n}$$

with the collection of Markov probability transitions :

$$K_{n+1, \eta_n} = S_{n, \eta_n} M_{n+1}$$

- Local transitions :

$$\mathbb{P}(\overline{X}_n \in dx_n \mid \overline{X}_{n-1}) = K_{n, \eta_{n-1}}(\overline{X}_{n-1}, dx_n) \quad \text{with} \quad \eta_{n-1} = \text{Law}(\overline{X}_{n-1})$$

- McKean measures (canonical process) :

$$\mathbb{P}_n(d(x_0, \dots, x_n)) = \eta_0(dx_0) K_{1, \eta_0}(x_0, dx_1) \dots K_{n, \eta_{n-1}}(x_{n-1}, dx_n)$$

Sampling pb \Rightarrow Mean field particle interpretations

- Markov Chain $\xi_n = (\xi_n^1, \dots, \xi_n^N) \in E_n^N$ s.t.

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\xi_n^i} \simeq_{N \uparrow \infty} \eta_n$$

- Approximated local transitions ($\forall 1 \leq i \leq N$)

$$\xi_{n-1}^i \rightsquigarrow \xi_n^i \sim K_{n, \eta_{n-1}^{\textcolor{red}{N}}}(\xi_{n-1}^i, dx_n)$$

Schematic picture : $\xi_n \in E_n^N \rightsquigarrow \xi_{n+1} \in E_{n+1}^N$

$$\begin{array}{ccc} \xi_n^1 & \xrightarrow{K_{n+1, \eta_n^N}} & \xi_{n+1}^1 \\ \vdots & & \vdots \\ \xi_n^i & \longrightarrow & \xi_{n+1}^i \\ \vdots & & \vdots \\ \xi_n^N & \longrightarrow & \xi_{n+1}^N \end{array}$$

Rationale :

$$\eta_n^N \simeq_{N \uparrow \infty} \eta_n \implies K_{n+1, \eta_n^N} \simeq_{N \uparrow \infty} K_{n+1, \eta_n} \implies \xi^i \sim \text{i.i.d. copies of } \bar{X}$$

\Downarrow

Particle McKean measures :

$$\frac{1}{N} \sum_{i=1}^N \delta_{(\xi_0^i, \dots, \xi_n^i)} \longrightarrow_{N \uparrow \infty} \text{Law}(\bar{X}_0, \dots, \bar{X}_n)$$

Feynman-Kac models \Leftrightarrow Genetic type stochastic algo.

$$\begin{bmatrix} \xi_n^1 \\ \vdots \\ \xi_n^i \\ \vdots \\ \xi_n^N \end{bmatrix} \xrightarrow{S_{n,\eta_n^N}} \begin{bmatrix} \widehat{\xi}_n^1 & \xrightarrow{M_{n+1}} & \xi_{n+1}^1 \\ \vdots & & \vdots \\ \widehat{\xi}_n^i & \xrightarrow{} & \xi_{n+1}^i \\ \vdots & & \vdots \\ \widehat{\xi}_n^N & \xrightarrow{} & \xi_{n+1}^N \end{bmatrix}$$

Acceptance/Rejection-Selection : [Geometric type clocks]

$$S_{n,\eta_n^N}(\xi_n^i, dx)$$

$$:= \epsilon_n G_n(\xi_n^i) \delta_{\xi_n^i}(dx) + (1 - \epsilon_n G_n(\xi_n^i)) \sum_{j=1}^N \frac{G_n(\xi_n^j)}{\sum_{k=1}^N G_n(\xi_n^k)} \delta_{\xi_n^j}(dx)$$

Ex. : $G_n = 1_A \rightsquigarrow G_n(\xi_n^i) = 1_A(\xi_n^i)$

Some key advantages

- Mean field models = stochastic linearization/perturbation technique :

$$\eta_n^N = \eta_{n-1}^N K_{n,\eta_{n-1}^N} + \frac{1}{\sqrt{N}} W_n^N$$

with $W_n^N \simeq W_n$ Centered Gaussian Fields \perp .

- $\eta_n = \eta_{n-1} K_{n,\eta_{n-1}}$ stable \Rightarrow No propagation of local sampling errors
 \implies Uniform control w.r.t. the time horizon
- "No burning, no need to study the stability of MCMC models".
- Stochastic adaptive grid approximation
- Nonlinear system \rightsquigarrow "positive-benefic interactions".
- Simple and natural sampling algorithm.

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 - Non asymptotic theorems
 - Unnormalized models
 - Additive functionals
- 6 Some references

"Asympt." theo. TCL,PGD, PDM \oplus (n,N) fixed \rightsquigarrow some examples :

- Empirical processes :

$$\sup_{n \geq 0} \sup_{N \geq 1} \sqrt{N} \mathbb{E}(\|\eta_n^N - \eta_n\|_{\mathcal{F}_n}^p) < \infty$$

- Concentration inequalities uniform w.r.t. time :

$$\sup_{n \geq 0} \mathbb{P}(|\eta_n^N(f_n) - \eta_n(f_n)| > \epsilon) \leq c \exp(-(N\epsilon^2)/(2\sigma^2))$$

+ Guionnet $\sup_{n \geq 0}$ (IHP 01) & Ledoux $\sup_{\mathcal{F}_n}$ (JTP 00) & Rio AAP 10

- Propagations of chaos exansions (+Patras,Rubenthaler (AAP 09)) :

$$\mathbb{P}_{n,q}^N := \text{Law}(\xi_n^1, \dots, \xi_n^q)$$

$$\simeq \eta_n^{\otimes q} + \frac{1}{N} \partial^1 \mathbb{P}_{n,q} + \dots + \frac{1}{N^k} \partial^k \mathbb{P}_{n,q} + \frac{1}{N^{k+1}} \partial^{k+1} \mathbb{P}_{n,q}^N$$

with $\sup_{N \geq 1} \|\partial^{k+1} \mathbb{P}_{n,q}^N\|_{\text{tv}} < \infty$ & $\sup_{n \geq 0} \|\partial^1 \mathbb{P}_{n,q}\|_{\text{tv}} \leq c q^2$.

Un-bias particle approximation measures

$$\gamma_n^N(f_n) := \eta_n^N(f_n) \prod_{0 \leq p < n} \eta_p^N(G_p)$$

- **Asymptotic theorems** : fluctuations & deviations
+ A. Guionnet (AAP 99, SPA 98), + L. Miclo (SP 00), + D. Dawson (01)
- **Non asymptotic theory** : bias and variance estimates
 - ① Taylor type expansion (+Patras & Rubenthaler (AAP 09) :

$$\mathbb{E} ((\gamma_n^N)^{\otimes q}(F)) =: \mathbb{Q}_{n,q}^N(F) = \gamma_n^{\otimes q}(F) + \sum_{1 \leq k \leq (q-1)(n+1)} \frac{1}{N^k} \partial^k \mathbb{Q}_{n,q}(F)$$

- ② Variance estimates (+Cerou & Guyader Hal-INRIA 08 & IPH 2010) :

$$\mathbb{E} \left([\gamma_n^N(f_n) - \gamma_n(f_n)]^2 \right) \leq c \frac{n}{N} \times \gamma_n(1)^2$$

Additive functionals

$$F_n(x_0, \dots, x_n) = \frac{1}{n+1} \sum_{0 \leq p \leq n} f_p(x_p)$$

- Bias estimate + uniform \mathbb{L}_p -bounds + variance $(1/N^2)$

$$N \mathbb{E} \left([(\mathbb{Q}_n^N - \mathbb{Q}_n)(F_n)]^2 \right) \leq c \times \begin{pmatrix} & \\ & \underbrace{1/n}_{\text{bias term}} & +1/N \end{pmatrix}$$

- Uniform exponential concentration

$$\frac{1}{N} \log \sup_{n \geq 0} \mathbb{P} \left(|[\mathbb{Q}_n^N - \mathbb{Q}_n](F_n)| \geq \frac{b}{\sqrt{N}} + \epsilon \right) \leq -\epsilon^2/(2b^2)$$

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Particle methods & Sequential Monte Carlo

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